

PARALLEL ARITHMETIC APPARATUS, ENTERTAINMENT APPARATUS,  
PROCESSING METHOD, COMPUTER PROGRAM AND  
SEMICONDUCTOR DEVICE

5                   CROSS-REFERENCE TO RELATED APPLICATIONS

This application is based upon and claims the benefit of priority from the prior Japanese Patent Applications No. 2000-335787, filed November 2, 2000, and No. 2001-318590 filed October 16, 2001, the entire contents of both of which are incorporated herein by reference.

10                  BACKGROUND OF THE INVENTION

Field of the Invention

The present invention relates to a technology for carrying out processing using a plurality of arithmetic units in parallel, for example, a parallel arithmetic processing technology for carrying out processing such as geometry processing which is executed on computer graphics at high speed.

Description of the Related Art

There are objects to be displayed with three-dimensional computer graphics which are modeled with a set of a plurality of basic graphics (polygons). The vertices of a polygon are expressed by four-dimensional coordinates (x, y, z, w) using homogeneous coordinates. The coordinates of the polygon vertices are subjected to coordinate transformation according to points of view coordinates and subjected to perspective transformation, etc. according to distances. That is, the coordinates of the polygon vertices are transformed in such a way that farther objects appear smaller. This series of processing is called

“geometry processing”.

There are various modes of geometry processing. For example, a matrix operation using a  $4 \times 4$  transformation matrix, etc. is performed on polygon rotation, expansion, contraction, perspective projection and 5 translating or an inner product operation is carried out to determine brightness on a light-receptive surface, etc. These matrix operations and inner product operations require repetitions of sum-of-products operations.

In three-dimensional computer graphics, a processing method 10 using floating-points conventionally used for high end systems is now also used in the field of entertainment apparatuses for generating entertainment images such as video game images and the field with severe constraints on costs such as portable information terminals. This is because the processing method using floating-points broadens the 15 data dynamic range and facilitates programming, and is therefore suited to sophisticated processing.

For the purpose of carrying out a matrix operation on floating-point numbers used for processing using floating-points, a parallel arithmetic apparatus is available which incorporates a plurality 20 of floating-point sum-of-products operator (FMAC: Floating Multiply ACCumulator) and carries out matrix operations efficiently. The ability of the parallel arithmetic apparatus to carry out operations in parallel using a plurality of FMACs increases the processing speed.

There are apparatuses carrying out three-dimensional image 25 processing such as an entertainment apparatus and personal computer that can obtain fine and real three-dimensional images at high speed by

carrying out aforementioned geometry processing using such a parallel arithmetic apparatus.

If this parallel arithmetic apparatus is provided with four FMACs placed in parallel, the parallel arithmetic apparatus can easily perform 5 matrix operations using a  $4 \times 4$  transformation matrix as shown in mathematical expression 1. However, it is difficult to perform an inner product operation between a vector A (Ax, Ay, Az, Aw) and vector B (Bx, By, Bz, Bw) shown in mathematical expression 2.

10 This is because the coordinates X, Y, Z and W subject to processing are independently operated in a one-to-one correspondence with four FMACs.

This will be explained more specifically.

15 When a matrix operation in mathematical expression 1 is carried out, component values corresponding to one row of the transformation matrix and coordinate values of the coordinates to be transformed are fed into each of four FMACs. The component values of the transformation matrix and coordinate values of the coordinates entered are subjected to a sum-of-products operation to perform a matrix operation. For example, component values (M11, M12, M13, M14) on the first row of the 20 transformation matrix and coordinate values of the coordinates (Vx, Vy, Vz, Vw) are subjected to a sum-of-products operation to calculate "M11· Vx+M12· Vy+M13· Vz+M14· Vw". Since each of the four FMACs carries out a similar sum-of-products operation, matrix operations are completed efficiently. In this Specification, "·" denotes a multiplication.

25 When an inner product operation in mathematical expression 2 is carried out, each of the four FMACs is associated with one of the

component values of the components X, Y, Z and W. Therefore, Ax and Bx, Ay and By, Az and Bz and Aw and Bw are input to each of the four FMACs respectively. Ax· Bx, Ay· By, Az· Bz and Aw· Bw are calculated as their respective outputs. Thus, executing mathematical expression 2

5 requires an adder for adding up the outputs of the four FMACs to be provided separately, which will increase the scale of the circuit.

Thus, the conventional parallel arithmetic apparatus can process matrix operations efficiently, but the FMACs provided in parallel alone cannot perform vector inner product operations, and in this way the

10 conventional parallel arithmetic apparatuses may require an additional adder.

(MATHEMATICAL EXPRESSION 1)

$$\begin{bmatrix} M_{11} & M_{12} & M_{13} & M_{14} \\ M_{21} & M_{22} & M_{23} & M_{24} \\ M_{31} & M_{32} & M_{33} & M_{34} \\ M_{41} & M_{42} & M_{43} & M_{44} \end{bmatrix} \begin{bmatrix} V_x \\ V_y \\ V_z \\ V_w \end{bmatrix} = \begin{bmatrix} M_{11} \cdot V_x + M_{12} \cdot V_y + M_{13} \cdot V_z + M_{14} \cdot V_w \\ M_{21} \cdot V_x + M_{22} \cdot V_y + M_{23} \cdot V_z + M_{24} \cdot V_w \\ M_{31} \cdot V_x + M_{32} \cdot V_y + M_{33} \cdot V_z + M_{34} \cdot V_w \\ M_{41} \cdot V_x + M_{42} \cdot V_y + M_{43} \cdot V_z + M_{44} \cdot V_w \end{bmatrix}$$

(MATHEMATICAL EXPRESSION 2)

15 
$$(Ax, Ay, Az, Aw) \cdot (Bx, By, Bz, Bw)$$
  

$$= Ax \cdot Bx + Ay \cdot By + Az \cdot Bz + Aw \cdot Bw$$

SUMMARY OF THE INVENTION

It is a main object of the present invention to provide a parallel arithmetic apparatus capable of carrying out vector inner product

20 operations easily while carrying out matrix operations as efficiently as the conventional parallel arithmetic apparatus.

In order to solve the above-described problems, the parallel arithmetic apparatus according to the present invention comprises a

plurality of pairs of recording means for recording arithmetical elements to be operated and operating means for performing sum-of-products operations based on the arithmetical elements recorded in the recording means, wherein one of said recording means of all pairs is selected and

5 selecting means for inputting the arithmetical elements recorded in the selected recording means to the operating means of the pair is inserted between the recording means and operating means of any one pair.

The parallel arithmetic apparatus of the present invention can, when the selecting means selects recording means of the pair in which

10 the selecting means itself is inserted, perform operations using arithmetical elements independent of each other in each pair. That is, it is possible to carry out matrix operations similar to the conventional art.

On the other hand, when the selecting means selects one recording means after another from among all the recording means in a

15 round-robin fashion, it is possible to perform operations using arithmetical elements recorded in the recording means of each pair. That is, the parallel arithmetic apparatus of the present invention can perform inner product operations easily without the need to use other circuits such as adders.

20 This parallel arithmetic apparatus can also insert temporary recording means for temporarily recording the arithmetical elements recorded in the recording means of a pair in which the selecting means is not inserted is inserted between the recording means and operating means of the pair. In this case, the selecting means is constructed in

25 such a way as to input the arithmetical elements recorded in the temporary recording means to the operating means when the recording

means of the pair in which the selecting means is not inserted is selected.

Inserting the temporary recording means eliminates the need to occupy the output ports of the recording means when arithmetical elements are taken in from the recording means. This allows the

5 recording means and operating means of the pair in which the temporary recording means is inserted to perform other processing.

In the parallel arithmetic apparatus, the recording means of all pairs record, during a matrix operation, a first arithmetical element to be subjected to the matrix operation, and during a vector inner product

10 operation, a second arithmetical element to be subjected to the vector inner product operation, the selecting means is constructed in such a way as to input the first arithmetical element from the recording means of the own pair to the operating means of the own pair, and during the inner product operation, in such a way as to select the recording means of all 15 the pairs one by one in a round-robin fashion and input the second arithmetical element from the selected recording means to the operating means of the own pair.

Each of the operating means performs operations with a content independently assigned to the pair using the operating elements recorded in the recording means of the pair and when this parallel arithmetic apparatus is used for three-dimensional computer graphics, such an operation is associated with any one of components of four-dimensional coordinates.

Another embodiment of the present invention is a parallel arithmetic apparatus that selectively performs a matrix operation and vector inner product operation, comprising a plurality of recording means

for recording, during the matrix operation, a first arithmetical element to be subjected to the matrix operation and recording, during the inner product operation, a second arithmetical element to be subjected to the inner product operation, a plurality of operating means forming a

5 one-to-one correspondence with the plurality of recording means for performing, during the matrix operation, a sum-of-products operation by each operating means inputting the first arithmetical element recorded in the corresponding recording means and performing, during the inner product operation, a sum-of-products operation by predetermined one of

10 the operating means inputting the second arithmetical element recorded in all the recording means and selecting means for selecting, during the matrix operation, the recording means corresponding to the predetermined operating means and inputting a first arithmetical element recorded in this recording means in the predetermined operating means, and selecting, during the inner product operation, the plurality of recording means one by one in a round-robin fashion and inputting a second arithmetical element recorded in the selected recording means in the predetermined operating means.

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In such a parallel arithmetic apparatus, the operating means is  
constructed so as to carry out a sum-of-products operation on the  
floating-point numbers when, for example, the arithmetical elements are  
expressed with floating-point numbers.

The entertainment apparatus according to the present invention is an entertainment apparatus that performs image processing on an entertainment image by performing a matrix operation with regard to coordinates expressing a position and shape of an object and performing

an inner product operation with regard to vectors used to express an image of the object, comprising a plurality of registers that records, during the matrix operation, a first arithmetical element subjected to the matrix operation and records, during the inner product operation, a

- 5 second arithmetical element subjected to the inner product operation, a plurality of sum-of-products operators forming a one-to-one correspondence with the plurality of registers that performs, during the matrix operation, a sum-of-products operation by each sum-of-products operator inputting the first arithmetical element recorded in the
- 10 corresponding registers, and performs, during the inner product operation, a sum-of-products operation by predetermined one of the sum-of-products operators inputting the second arithmetical element recorded in all registers and a selector that selects, during the matrix operation, a register corresponding to the predetermined
- 15 sum-of-products operator and inputs a first arithmetical element recorded in this register in the predetermined sum-of-products operator, and selects, during the inner product operation, the plurality of registers one by one in a round-robin fashion and inputs a second arithmetical element recorded in the selected register in the predetermined
- 20 sum-of-products operator.

Another embodiment of the present invention is an entertainment apparatus that performs image processing on an entertainment image by carrying out a matrix operation between a matrix and coordinate values to perform a coordinate transformation of coordinates expressing the

- 25 position and shape of an object and carrying out an inner product operation between a normal vector oriented in the normal direction of the

surface of the object and position vector of a light source to determine the display mode of the surface of the object, comprising a plurality of registers that records the coordinate values and component values corresponding to any one row of the matrix during the matrix operation

5 and records the normal vector and component values corresponding to any one component of the position vector during the inner product operation, a sum-of-products operators forming a one-to-one correspondence with the plurality of registers that carries out a sum-of-products operation during the matrix operation by each

10 sum-of-products inputting the coordinate values recorded in the corresponding register and component values corresponding to the one row of the matrix, and carry out a sum-of-products operation during the inner product operation by predetermined one of the sum-of-products operators inputting the normal vector recorded in all registers and

15 component values of the position vector, a selector that selects, during the matrix operation, a register corresponding to the predetermined sum-of-products operator and inputs the coordinate value recorded in this register and component values corresponding to the one row of the matrix to the predetermined sum-of-products operator, and selects,

20 during the inner product operation, the plurality of registers one by one in a round-robin fashion and inputs component values of the normal vector and the position vector recorded in the selected register in the predetermined sum-of-products operator.

The processing method according to the present invention is a

25 processing method that allows a matrix operation and vector inner product operation to be selectively executed and is executed by an

apparatus provided with a plurality of operating means, comprising the steps of inputting, during the matrix operation, arithmetical elements subjected to the matrix operation by assigning the arithmetical elements to the plurality of operating means based on the features thereof to carry

5 out a sum-of-products operation based on the assigned arithmetical elements and inputting, during the inner product operation, arithmetical elements subjected to the inner product operation in one predetermined operating means to allow the operating means to carry out a sum-of-products operation based on the arithmetical elements.

10 The computer program according to the present invention is a computer program that makes it possible to selectively execute a matrix operation and vector inner product operation and renders a computer provided with a plurality of operating means to execute a step of inputting, during the matrix operation, arithmetical elements subjected to the matrix operation by assigning the arithmetical elements to the plurality of operating means based on the features thereof to carry out a sum-of-products operation based on the assigned arithmetical elements and inputting, during the inner product operation, arithmetical elements subjected to the inner product operation in one predetermined operating

15 means to allow the operating means to carry out a sum-of-products operation based on the arithmetical elements.

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25 The semiconductor device according to the present invention is a semiconductor device that makes it possible to selectively execute a matrix operation and vector inner product operation and is built in an apparatus incorporating a computer provided with a plurality of operating means, rendering the apparatus to execute a step of inputting,

5 during the matrix operation, arithmetical elements subjected to the matrix operation by assigning the arithmetical elements to the plurality of operating means based on the features thereof to allow each operating means to carry out a sum-of-products operation based on the assigned arithmetical elements and inputting, during the inner product operation, 10 arithmetical elements subjected to the inner product operation in one predetermined operating means to allow the operating means to carry out a sum-of-products operation based on the arithmetical elements.

#### BRIEF DESCRIPTION OF THE DRAWINGS

10 These objects and other objects and advantages of the present invention will become more apparent upon reading of the following detailed description and the accompanying drawings in which:

15 FIG. 1 is a block diagram of an entertainment apparatus;

FIG. 2 is a block diagram of a parallel arithmetic apparatus;

FIG. 3 is an internal block diagram of an FMAC;

FIG. 4 is a flow chart showing a procedure for inner product operation processing; and

FIG. 5 is a block diagram of a parallel arithmetic apparatus.

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

20 An embodiment of the present invention will be specifically described with reference to the drawings accompanying herewith.

FIG. 1 illustrates a configuration example of an entertainment apparatus including a parallel arithmetic apparatus according to the present invention.

25 This entertainment apparatus 1 is provided with two buses, a main bus B1 and a sub bus B2, to which a plurality of semiconductor

devices each having a specific function is connected. These buses B1 and B2 are mutually connected or disconnected via a bus interface INT.

The main bus B1 is connected with a main CPU 10 which is a main semiconductor device, a main memory 11 made up of a RAM, a 5 main DMAC (Direct Memory Access Controller) 12, an MPEG (Moving Picture Experts Group) decoder (MDEC) 13 and a graphic processing unit (hereinafter referred to as "GPU") 14 having a built-in frame memory 15 which serves as a drawing memory. The GPU 14 is connected with a CRTC (CRT controller) 16 for generating a video output signal so that the 10 data drawn in the frame memory 15 can be displayed on a display apparatus (not shown).

The CPU 10 loads a start program from the ROM 23 on the sub bus B2 at the startup of the entertainment apparatus 1 via the bus interface INT, executes the start program and operates an operating 15 system. The CPU 10 also controls the media drive 27, reads an application program or data from the medium 28 mounted in this media drive 27 and stores this in the main memory 11. The CPU 10 further applies the above-described geometry processing to various data read from the medium 28, for example, three-dimensional object data 20 (coordinate values of vertices (typical points) of a polygon, etc.) made up of a plurality of basic graphics (polygons) and generates a display list containing geometry-processed polygon definition information (specifications of shape of the polygon used, its drawing position, type, color or texture, etc. of components of the polygon).

25 The parallel arithmetic apparatus 100 is included in this main CPU 10 and used when geometry processing, etc. is carried out. Details

of the parallel arithmetic apparatus 100 will be described later.

The GPU 14 is a semiconductor device having the functions of storing drawing context (drawing data including polygon components), carrying out rendering processing (drawing processing) by reading

5 drawing context according to the display list notified from the main CPU 10 and drawing polygons in the frame memory 15. The frame memory 15 can also be used as a texture memory. Thus, a pixel image in the frame memory can be pasted as texture to a polygon to be drawn.

The main DMAC 12 is a semiconductor device that carries out  
 10 DMA transfer control over the circuits connected to the main bus B1 and also carries out DMA transfer control over the circuits connected to the sub bus B2 according to the condition of the bus interface INT. The MDEC 13 is a semiconductor device that operates in parallel with the CPU 10 and has the function of expanding data compressed in MPEG  
 15 (Moving Picture Experts Group) or JPEG (Joint Photographic Experts Group) systems, etc.

The sub bus B2 is connected to a sub CPU 20 made up of a microprocessor, etc., a sub memory 21 made up of a RAM, a sub DMAC 22, a ROM 23 that records a control program such as an operating system, a sound processing semiconductor device (SPU: Sound Processing Unit) 24 that reads sound data stored in the sound memory 25 and outputs as audio output, a communication control section (ATM) 26 that transmits/receives information to/from an external apparatus via a network (not shown), a media drive 27 for setting a medium 28 such  
 20 as CD-ROM and DVD-ROM and an input device 31.

The sub CPU 20 carries out various operations according to the

control program stored in the ROM 23. The sub DMAC 22 is a semiconductor device that carries out control such as a DMA transfer over the circuits connected to the sub bus B2 only when the bus interface INT separates the main bus B1 from sub bus B2. The input device 31 is 5 provided with a connection terminal 32 through which an input signal from an operating device 33 is input.

The entertainment apparatus 1 in such a configuration can carry out matrix operations and inner product operations carried out during geometry processing at high speed through the parallel arithmetic

10 apparatus 100 included in the main CPU 10, which will be described below.

The parallel arithmetic apparatus 100 executes at high speed a matrix operation between a transformation matrix and vertex coordinate values carried out when coordinates of polygon vertices are transformed 15 and an inner product operation between a normal vector oriented in the normal direction of the surface and a position vector of a light source carried out when a display condition such as brightness of the surface of an object is determined.

<Embodiment 1>

20 FIG. 2 shows a configuration example of the parallel arithmetic apparatus 100 included in the main CPU 10.

This parallel arithmetic apparatus 100a acquires coordinate values of polygon vertices and data (arithmetical elements) necessary for geometry processing such as a transformation matrix used for matrix 25 operations from the main memory 11 via the main bus B1 and carries out operations.

The parallel arithmetic apparatus 100a is constructed by including a control circuit 110, registers 120a to 120d, selectors 130a and 130b, FMACs 140a to 140d as arithmetic units and an internal storage device 150. The registers 120a to 120d and the internal storage device 150 are connected via the internal bus B.

The registers 120a to 120d each form a pair with the FMACs 140a to 140d, that is, the registers are designed to have a one-to-one correspondence with the FMACs. To realize matrix operations using a  $4 \times 4$  transformation matrix and inner product operations of four-dimensional vectors, this embodiment uses four pairs of register and FMAC, but the number of pairs can be determined according to the processing content as appropriate.

Selectors 130a and 130b are provided between the register 120a and FMAC 140a.

This embodiment expresses arithmetical elements used for matrix operations and inner product operations using floating-point numbers, but it goes without saying that fixed-point numbers can also be used instead. When arithmetical elements are expressed with fixed-point numbers, sum-of-products operators for fixed-point numbers will be used instead of the FMACs 140a to 140d.

The control circuit 110 controls the overall operation of the parallel arithmetic apparatus 100a. For example, the control circuit 110 controls the recording of arithmetical elements in the registers 120a to 120d and the operations of the selectors 130a and 130b.

The registers 120a to 120d take in and record arithmetical elements assigned to the respective registers from among the arithmetical

elements such as component values of a transformation matrix used for operations such as matrix operations or inner product operations, coordinate values of coordinates to be transformed and vector component values from the internal storage device 150 under the control of the

5 control circuit 110.

When an inner product operation of four-dimensional vectors is carried out, the registers 120a to 120d take in and record component values assigned to the respective registers as arithmetical elements from among component values of two four-dimensional vectors. For example, 10 of the two four-dimensional vectors (Ax, Ay, Az, Aw) and (Bx, By, Bz, Bw), the register 120a records components values Ax and Bx, the register 120b records components values Ay and By, the register 120c records components values Az and Bz and the register 120d records components values Aw and Bw.

15 When a matrix operation is carried out using a  $4 \times 4$  transformation matrix, the registers 120a to 120d take in and record, as arithmetical elements, the coordinate values of the four-dimensional coordinates to be transformed and component values of a row assigned to the respective registers of the transformation matrix. For example, the 20 registers 120a to 120d record component values of the transformation matrix in addition to coordinate values of the four-dimensional coordinates; the register 120a records the component values of the 1st row of the transformation matrix, the register 120b records the component values of the 2nd row of the transformation matrix, the 25 register 120c records the component values of the 3rd row of the transformation matrix and the register 120d records the component

values of the 4th row of the transformation matrix as their respective arithmetical elements. The registers 120a to 120d each record a pair of the 1st column component value of each row of the transformation matrix and the 1st component value of the four-dimensional coordinate to be transformed, a pair of the 2nd column component value and the 2nd component value, a pair of the 3rd column component value and the 3rd component value and a pair of the 4th column component value and the 4th component value, and these values are read one pair at a time.

Furthermore, the registers 120a to 120d record calculation results of the FMACs 140a to 140d each forming a pair with the registers 120a to 120d.

The selectors 130a and 130b select one of the registers 120a to 120d, take in an arithmetical element to be recorded in the selected register and supply the arithmetical element to the FMAC 140a. When an inner product operation is carried out, the selectors 130a and 130b select one of the registers 120a to 120d in a round-robin fashion, take in an arithmetical element to be recorded in the selected register and supply the arithmetical element to the FMAC 140a. When a matrix operation is carried out, the selectors 130a and 130b always select the register 120a and take in the arithmetical element recorded in the register 120a and supply the arithmetical element to the FMAC 140a.

The selectors 130a and 130b select a register indicated by the control circuit 110 based on the content of an operation carried out at that time and the situation of progress of the operation, etc.

25 The FMACs 140a to 140d take in two arithmetical elements  
recorded in the registers 120a to 120d and multiply and add up the two

arithmetical elements.

FIG. 3 is an internal block diagram of the FMAC 140a. Since the other FMACs 140b to 140d also have the same configuration, only the configuration of the FMAC 140a will be explained here and explanations of the other FMACs 140b to 140d will be omitted.

In order to multiply and add up the arithmetical elements taken in, the FMAC 140a is provided with a floating-point number multiplier (FMUL: Floating MULtiply) 141 and a floating-point number adder (FADD: Floating ADDer) 142. The two arithmetical elements taken in are multiplied by the FMUL 141 first. The multiplication result is sent to the FADD 142. The FADD 142 adds up the multiplication results sent from the FMUL 141 one by one.

For example, when  $a_0$  to  $a_n$  and  $b_0$  to  $b_n$  are taken in one after another as arithmetical elements, the FMAC 140a obtains the following calculation result:

$$a_0 \cdot b_0 + a_1 \cdot b_1 + a_2 \cdot b_2 + \dots + a_{(n-1)} \cdot b_{(n-1)} + a_n \cdot b_n$$

The FMACs 140a to 140d output the calculation results to the registers that form their respective pairs.

Using the selectors 130a and 130b, the FMACs 140a to 140d perform the following operations during an inner product operation and matrix operation.

When an inner product operation is carried out, the FMAC 140a multiplies component values of the components of two vectors supplied from the registers 120a to 120d via the selectors 130a and 130b and adds up the multiplication results one by one. Furthermore, it is also possible to count the number of times these multiplications and

additions are performed, make the situation of progress of the inner product operation visible and prevent the next instruction from starting until the inner product operation is completed.

When a matrix operation is carried out, the FMACs 140a to 140d

5 multiply component values of the transformation matrix taken in from the corresponding registers 120a to 120d by coordinate values of the four-dimensional coordinates which form pairs and add up the multiplication results one by one.

The internal storage device 150 takes in coordinate values of

10 polygon vertices, component values of the transformation matrix used for matrix operations, data necessary for geometry processing of vector component values, etc. from the main memory 11 and records these values under the control of the control circuit 110. Furthermore, the internal storage device 150 takes in and records the calculation results 15 from the registers 120a to 120d. The calculation results are sent to the main memory 11 via the internal storage device 150.

A direct memory access transfer is performed between the internal storage device 150 and the main memory 11, which allows high speed data transmission/reception and is convenient for processing of images, 20 etc. which requires large-volume data processing.

The processing procedure when the parallel arithmetic apparatus 100a carries out the inner product operation in mathematical expression 2, that is, the inner product operation between vector A (Ax, Ay, Az, Aw) 25 and vector B (Bx, By, Bz, Bw) will be explained. FIG. 4 is a flow chart showing such a processing procedure.

The parallel arithmetic apparatus 100a takes in the component

values of the vector A (Ax, Ay, Az, Aw) and vector B (Bx, By, Bz, Bw) stored in the main memory 11 through a direct memory access transfer and records the component values in the internal storage device 150 (step S101).

5 The registers 120a to 120d take in the component values assigned to the respective registers from among the component values of the vector A (Ax, Ay, Az, Aw) and vector B (Bx, By, Bz, Bw) stored in the internal storage device 150. That is, the register 120a takes in Ax and Bx, the register 120b takes in Ay and By, the register 120c takes in Az and Bz and 10 the register 120d takes in Aw and Bw (step S102).

The selectors 130a and 130b select one of the registers 120a to 120d, take in the component values of vector A and vector B to be recorded in the selected register and supply the component values to the FMAC 140a. The control circuit 110 determines which of the registers 15 120a to 120d should be selected according to the situation of progress of the inner product operation. The selectors 130a and 130b select one of the registers 120a to 120d under the control of the control circuit 110. Here, the selectors 130a and 130b select the register 120a, take in Ax and Bx and supply Ax and Bx to the FMAC 140a, first (step S103). The 20 FMAC 140a performs a sum-of-products operation between Ax and Bx using the FMUL 141 and FADD 142 (step S104). Before the first sum-of-products operation is carried out, the internal state of the FMAC 140a is cleared.

After the sum-of-products operation, the FMAC 140a determines 25 whether the inner product operation has been completed or not (step S105). Whether the inner product operation has been completed or not

can be determined by knowing the number of component values of vectors subjected to the inner product operation. The number of times a sum-of-products operation is performed is counted and it is when the count equals to the number of component values of vectors input that it

5 is determined that the inner product operation has been completed.

This makes it possible to know from the count the register from which the next component value should be extracted. The result of determination as to whether the inner product operation has been completed or not is sent to the control circuit 110.

10 In this case, the inner product operation has not been completed yet (step S105: N), and therefore the control circuit 110 allows the selectors 130a and 130b to select the register 120b. The selectors 130a and 130b select the register 120b under the control of the control circuit 110, take in Ay and By and supply Ay and By to the FMAC 140a. When  
 15 the FMAC 140a takes in Ay and By, the FMUL 141 and FADD 142 perform a sum-of-products operation to obtain Ax· Bx+Ay· By. Likewise, step S103 to step S105 are repeated until the inner product operations are completed to obtain Ax· Bx+Ay· By+Az· Bz+Aw· Bw.

Upon determining that the inner product operations have been  
 20 completed (step S105: Y), the FMAC 140a outputs the calculation result to the register 120a (step S106). After the output, the FMAC 140a clears the internal state (step S107). The output calculation result is input from the register 120a to the internal storage device 150 and sent to the main memory 11.

25 This completes the inner product operations.

Providing the selectors 130a and 130b allows calculations

between component values of different components making it easier to carry out inner product operations. The selectors 130a and 130b are provided between the register 120a and FMAC 140a, but this embodiment is not limited to this, and the selectors 130a and 130b can

5 also be provided between the register 120b and FMAC 140b, between the register 120c and FMAC 140c or between the register 120d and FMAC 140d.

When a matrix operation is performed, the selectors 130a and 130b always select the register 120a, only supply the arithmetical

10 element recorded in the register 120a to the FMAC 140a and never supply the arithmetical elements recorded in the other registers 120b to 120d to the FMAC 140a. The arithmetical elements recorded in the other registers 120b to 120d are taken into the FMACs 140b to 140d with which the registers 120b to 120d form their respective pairs and  
15 processed.

For example, when the matrix operation in mathematical expression 1 is carried out, the register 120a records the component values (M11, M12, M13, M14) of the 1st row of the transformation matrix and the coordinate values (Vx, Vy, Vz, Vw) of the four-dimensional coordinates. The register 120b records the component values (M21, M22, M23, M24) of the 2nd row of the transformation matrix and the coordinate values (Vx, Vy, Vz, Vw) of the four-dimensional coordinates. The register 120c records the component values (M31, M32, M33, M34) of the 3rd row of the transformation matrix and the coordinate values (Vx, Vy, Vz, Vw) of the four-dimensional coordinates. The register 120d records the component values (M41, M42, M43, M44) of the 4th row of

the transformation matrix and the coordinate values (Vx, Vy, Vz, Vw) of the four-dimensional coordinates.

The FMACs 140a to 140d sequentially take in the component values and coordinate values recorded in the registers 120a to 120d with which the FMACs 140a to 140d form their respective pairs and carry out operations. Suppose the FMAC 140a is taken as an example. The FMAC 140a takes in M11 and Vx from the register 120a via the selectors 130a and 130b and calculates  $M11 \cdot Vx$  using the FMUL 141. The FMACs 140a sends this to the FADD 142. Then, the FMACs 140a takes in M12 and Vy and calculates  $M12 \cdot Vy$ , sends this to the FADD 142 and calculates  $M11 \cdot Vx + M12 \cdot Vy$ . Then, FMACs 140a carries out the same calculation on M13 and Vz, and M14 and Vw and calculates  $M11 \cdot Vx + M12 \cdot Vy + M13 \cdot Vz + M14 \cdot Vw$ . The other FMACs 140b to 140d carry out the same operations. Thus, the FMACs 140a to 140d carry out operations in parallel executing thereby  $4 \times 4$  matrix operations at the same speed as the conventional art.

As described above, the parallel arithmetic apparatus 100a is an apparatus that selectively carries out a matrix operation and vector inner product operation. The parallel arithmetic apparatus 100a is provided with at least the registers 120a to 120d that record component values of a transformation matrix as arithmetical elements during the matrix operation and record vector component values as arithmetical elements during the inner product operation, the FMACs 140a to 140d that take in the arithmetical elements recorded in the registers 120a to 120d and carry out sum-of-products operations, selectors 130a and 130b that select one register from the registers 120a to 120d and supply the

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arithmetical elements registered in the selected register to the FMAC 140a. The registers 120b to 120d form a one-to-one correspondence with the FMACs 140b to 140d. The selectors 130a and 130b supply component values of the transformation matrix recorded in the register 120a to the FMAC 140a during the matrix operation and select the registers 120a to 120d one by one in a round-robin fashion and supply the vector component value recorded in the selected register to the FMAC 140a during the inner product operation.

5 Providing the selectors 130a and 130b in this way makes it possible to carry out the matrix operation and inner product operation 10 selectively.

**<Embodiment 2>**

FIG. 5 is a block diagram of a parallel arithmetic apparatus 100b according to another embodiment.

15 Compared to the parallel arithmetic apparatus 100a shown in FIG. 2, the parallel arithmetic apparatus 100b is only different in that temporary registers 160b to 160d are provided at the output ends of the registers 120b to 120d.

This parallel arithmetic apparatus 100b is constructed of registers 20 120a to 120d that record arithmetical elements, FMACs 140a to 140d that carry out sum-of-products operations based on the arithmetical elements recorded in these registers 120a to 120d, selectors 130a and 130b inserted between the register 120a and FMAC 140a and temporary registers 160b to 160d inserted between the registers 120b to 120d and 25 the FMAC 140b to 140d. The selectors 130a and 130b select one from among the register 120a and the temporary registers 160b to 160d and

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inputs the arithmetical element recorded in the selected register 120a or temporary register 160b to 160d to the FMAC 140a. Operations of these components are controlled by the control circuit 110.

The temporary registers 160b to 160d have a one-to-one correspondence with the registers 120b to 120d. The temporary registers 160b to 160d temporarily store the arithmetical elements recorded in their respective registers 120b to 120d when these are sent to the FMAC 140b to 140d or the selectors 130a and 130b.

Since the temporary registers 160b to 160d temporarily record the arithmetical elements from the registers 120b to 120d, even if the arithmetical elements are not taken from the registers 120b to 120d into the FMAC 140a at the same timing as in the case of the inner product operation, the read ports of the registers 120b to 120d are not occupied by the arithmetical elements for inner product operations. Thus, while the FMAC 140a is carrying out a matrix operation, the other FMAC 140b to 140d take in the next arithmetical elements from the registers 120b to 120d, allowing a sum-of-products operation.

The above-described embodiments have described the entertainment apparatus using the parallel arithmetic apparatus 100 as an example, but the present invention is not limited to this and the parallel arithmetic apparatus of the present invention can use any information processor which carries out parallel arithmetic processing and carries out at least matrix operations and vector inner product operations. Moreover, the number of pairs of register and sum-of-product operator (FMAC) is not limited to 4, but that number of pairs can be determined according to the processing carried out by the

relevant apparatus.

Furthermore, the parallel arithmetic apparatus 100 can also be implemented by rendering a computer to execute the computer program of the present invention. This embodiment forms functional blocks corresponding to the selectors 130a and 130b on the computer with a plurality of FMACs through a co-operation between the computer program recorded in a computer-accessible recording medium such as a disk device or semiconductor memory and a control program (OS, etc.) incorporated in the computer.

As described above, the present invention can perform vector inner product operations easily while performing matrix operations as efficiently as the conventional art.

Various embodiments and changes may be made thereunto without departing from the broad spirit and scope of the invention. The above-described embodiment intended to illustrate the present invention, not to limit the scope of the present invention. The scope of the present invention is shown by the attached claims rather than the embodiment. Various modifications made within the meaning of an equivalent of the claims of the invention and within the claims are to be regarded to be in the scope of the present invention.